

## LG VACUUMS

# VR65704LVM

## LG Hom-Bot Square Robotic Vacuum

Corner Master

Dual Eye 2.0™ Mapping System

Collision-Safe Digital Bumper

7 Smart Cleaning Modes

Easy-Out Dust Bin

Low Noise Level

Smart Resume Function

Sweep + Vacuum + Mop

Large Slide-in Mop

Scheduled Cleaning

Voice Alerts

Long Lasting Battery

Touch Controls

Remote Control

Battery Charge Docking Station



SPECIFICATIONS	
Consumption Power	58W
Running time	approx. 100min (based on general wooden floor)
Charging time	3hr
Cleaning Extent m <sup>2</sup> (without recharging)	150m <sup>2</sup>
Upper Camera	CV SLAM
Lower Camera	OFS
Smart Diagnosis	•
BATTERY	
Type	Lithium
Capacity	14.4V / 2330mAh
Self Discharging rate	<<5% / month
CHARGER	
Rating Electrocitry	17.1V / 1.7A/30W
CLEANING MODE	
Number of Cleaning Mode	7
Zigzag	•
Cell by Cell	•
Spot (Spiral)	•
My Space	•
Turbo	•
Smart Turbo	•
Repeat	•
NOISE LEVEL(IEC)	
IEC (Normal)	60dB
IEC (Turbo)	68dB
NAVIGATION	
System	Robonavi10.0
Method	Absolute / SLAM / Kidnap
Localization Sensors	Vision / Gyro / OFS
Learning Function	•
Kidnap	•
Button Lock	•

OBSTACLE DETECTION	
Barrier Sensing Ability	10mm ↑
CLEANING PERFORMANCE	
Hard Floor	90%
Carpet	40%
OBSTACLE SENSORS	
OFS (Lower Camera)	•
Gyro	•
USS (Ultrasonic Sensor)	1T / 2R (2-Pair)
PSD (Position Sensitive Detector) Qty	2
Cliff (Qty)	3
Accelerometer Sensor	•
Side Brush (Qty)	2
Carpet (Cil) Overcome Height	1.5cm
Dry Mopping	•
Dust Bin Capacity	0.6L
Filter Type	EPA11
VOICE ALERT	
Guide	•
Speaking Sentence	106
Voice Guide Language	English, French, German, Spanish, Italian, Dutch, Danish
Mute	•
Remote Control	•
Power Saving Function	•
USER INTERFACE	
Display	LED Module
Button	Touch
ACCESSORY	
Carpet Brush	•
Mop	2
Mop Plate	•
Extra Filter	•
Extra Side Brush	2
Cleaning Brush	•
Cleaning Tool	•

DIMENSIONS / WEIGHT (WXDXH)	
Body (WxHxD)	13.39" x 3.5" x 13.39"
Packing (WxHxD)	17.44" x 6.42" x 21.45"
Net Weight (lbs)	6.6
Packing Weight (lbs)	12.3
LIMITED WARRANTY	
Limited Warranty	1 Year Parts & Labor
UPC CODES	
VR65704LVM Ocean Black	048231016018