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When using the X-Star/X-Star Premium, always refer to and follow the safety instructions in this manual. Autel Robotics takes no responsibility and accepts no warranty for direct or indirect product damage or injury if the user fails to follow the safety instructions. Autel Robotics will not be liable for any direct damages or for any legal, special, incidental, indirect damages or for any financial consequences (including the loss of profits).

The safety instructions herein covers situations which Autel Robotics is aware of. Autel Robotics cannot know, evaluate or advise you as to all of the possible hazards. You must be certain that any condition or service procedure encountered do not jeopardize your personal safety.

Safety Information

**IMPORTANT**

Before operating or maintaining this unit, please read this manual carefully, paying extra attention to the safety warnings and precautions.

For your own safety and the safety of others, and to prevent damaging the product...
WARNING

If any part of the aircraft (including motor, battery, gimbal, compass, propellers, LED lights, binding buttons, etc.) or the remote controller fails to function properly or has visible/invisible damages, DO NOT FLY THE AIRCRAFT.

Battery Usage

The aircraft is powered by a Lithium-Polymer battery. LiPo/Li-Ion batteries can be extremely hazardous and special attention is required during usage.

Read and follow carefully all safety messages and instructions presented to avoid personal injury or property damage.

WARNING

The Lithium-Polymer battery is factory replaceable only; incorrect replacement or tampering with the battery pack may cause an explosion.

- Use only the battery and battery charger provided by Autel Robotics. An unqualified battery or charger may present a risk of fire, explosion, leakage, or other hazards. Autel Robotics takes no responsibility for any damage caused by non-Autel-Robotics batteries or charging devices.

- Always turn off the aircraft before installing or removing the battery.

- Remove the battery before assembly or when not in use.

- Keep the battery away from water or any kind of liquid. If the battery gets in touch with liquid, it may lead to an explosion while using or charging.

- Do not expose the battery to fire, explosion or other hazards.

- Do not disassemble, open, crush, bend, deform, puncture or shred the battery.

- Do not modify, remanufacture, or attempt to insert foreign objects into the battery.

- Do not place heavy objects on the batteries or charger.

- Stop using or charging the battery immediately whenever the battery starts to swell, smoke or leak.

- Use the battery in temperatures between -10°C and 40°C. Extremely high temperatures may cause a fire or explosion, extremely low temperatures may lead to permanent battery damage.

- Do not use the battery in strong electrostatic or electromagnetic environments. Electrostatic or electromagnetic interference may lead to serious accidents during flight.

- Keep the battery out of reach of children and pets.

- Do not leave the battery close to moist or heat sources. Store the battery in a
dry and ventilated area at room temperature (ideally 22°C-28°C).

- Do not place the battery beside hard or sharp items, or on a conductive surface (e.g., metal plate).
- Do not place the battery in wet grass or in the pocket with metal objects.
- Battery electrolytes are highly corrosive. If any electrolytes make contact with your skin or eyes, immediately wash the affected area with fresh running water and see a doctor.
- Remove the battery from the aircraft immediately if the aircraft falls into water during flight. Leave the battery in an open area and keep a safe distance away until it is completely dry. Never use and charge the battery again.
- Do not use a damaged battery charger.
- Disconnect the charger when not in use and examine the charger’s condition regularly.
- Do not leave the charging battery unattended.
- Do not charge the battery immediately after using it, as overheat protection will be activated to prevent the battery from being charged before it has cooled down completely.
- The battery recharging time varies depending on the remaining battery level.
- Disconnect and remove the Li-Po battery from the aircraft after use to prevent trickle discharge. During storage, make sure the battery level does not fall below 3V.
- Since over charging may shorten the battery life, please unplug the charger once the aircraft and remote controller have been fully charged.
- The heavier the payload, the shorter the flight time will be as more battery power may be consumed.
- Using or storing the battery in extreme environments may reduce battery life.
- Battery life inevitably shortens over time. And battery life may be reduced if the battery is left unused over extended periods of time.
- Completely discharge the battery before disposal.
- Dispose the battery properly at specified battery recycling locations.

**Reminders**

- Flying with an experienced pilot for the first flight is strongly recommended.
- Keep small or electrical parts out of the reach of children.
- Keep away from heat sources or humid and hostile environments.
- Check the weather before flying, including air temperature and wind speed.
- Make a thorough preflight check before each flight (27)
- Use only authorized accessories approved or provided by Autel Robotics.
- Do not attempt to disassemble, modify or reconstruct any part of the devices. Autel Robotics will not be responsible for damages resulting from any artificial reason.
- Do not use this product for illegal purposes.

**Services and Support**

- [www.autelrobotics.com](http://www.autelrobotics.com)
- (844)-898-0290 (U.S.A.)
- support@autelrobotics.com

Or contact your local retail agent for technical assistance.
Before Starting

Using This Manual
Thank you for purchasing Autel Robotics’ product X-Star/X-Star Premium. Please read the manual carefully before you use the smart drone and retain the manual for future reference. Should your smart drone fail to operate correctly, refer to Troubleshooting Tips (58).

Legend

⚠️ WARNING: Precautions of a potentially hazardous situation which if not avoided could result in personal injury or property damage.

⚠️ IMPORTANT: Important information that demands special attention related to the smart drone’s operation.

заметка: Additional information that complement the current topic.

 REFERENCES: A page number that guides you to the section containing relevant information in this manual.

Before Your First Flight
Download the X-Star/X-Star Premium app Starlink™ from the App Store or Google Play and install the app on your mobile device.

Read the following documents before using the X-Star/X-Star Premium:
- X-Star/X-Star Premium Quick Guide
Getting to Know the Smart Drone

The X-Star series is a new generation of smart unmanned aerial vehicle, featuring easy operation and high stability. With the advanced built-in Smart Flight System, a high-performance remote controller, and a powerful mobile app, the X-Star allows safe and stable flight maneuvers which can be operated both manually and automatically. The stabilized 3-axis camera gimbal offers ideal solutions for smooth aerial photographing and video recording, making the system incredibly versatile and powerful.

The X-Star series comes in two models: the X-Star and X-Star Premium, which are both equipped with an integrated 4k camera gimbal. The X-Star adopts a self-generated WiFi network, while the X-Star Premium utilizes HD video streaming to establish a live video link with the mobile app Starlink™ as you fly.

This manual elaborates in detail on the functions and operations of the X-Star and the X-Star Premium.

**Aircraft**

The X-Star/X-Star Premium aircraft is a quadcopter with an integrated stabilized camera gimbal. An HD camera is also integrated.

**Functionality Description**

<table>
<thead>
<tr>
<th>Module</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Propeller</td>
<td>An electronic device consisting of a 3-axis gyroscope and a 3-axis accelerometer that measure the acceleration and angular rates of the aircraft. An automatic IMU calibration is performed every time you start the aircraft.</td>
</tr>
<tr>
<td>Motor</td>
<td>Measures geomagnetic field and provides heading reference to the aircraft.</td>
</tr>
<tr>
<td>Front LED Indicator Light</td>
<td>Receives GNSS (GPS/GLONASS) signals to determine the latitude, longitude and altitude of the aircraft.</td>
</tr>
<tr>
<td>Micro-USB Port</td>
<td></td>
</tr>
<tr>
<td>3-axis Gimbal</td>
<td></td>
</tr>
<tr>
<td>Camera</td>
<td></td>
</tr>
<tr>
<td>Front Sticker</td>
<td></td>
</tr>
<tr>
<td>Rear LED Indicator Light</td>
<td></td>
</tr>
<tr>
<td>Aircraft Battery</td>
<td></td>
</tr>
<tr>
<td>Compass Module</td>
<td></td>
</tr>
<tr>
<td>Starpoint™ Positioning Module</td>
<td></td>
</tr>
<tr>
<td>Landing Gear</td>
<td></td>
</tr>
<tr>
<td>Compass</td>
<td></td>
</tr>
</tbody>
</table>
Barometer: Measures atmospheric pressure to determine the pressure altitude of the aircraft.

Ultrasonic Sensors: Measures the distance between the aircraft and the ground.

Monochrome Camera: Tracks the x- and y-axis location of the moving aircraft relative to the ground.

### Smart Flight System Functions

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IOC</td>
<td>Configures the aircraft to fly in the direction relative to the home point. ([31] 31)</td>
</tr>
<tr>
<td>Go Home</td>
<td>Commands the aircraft to return and land at the specified home point. ([32] 32)</td>
</tr>
<tr>
<td>Failsafe</td>
<td>Enables the aircraft to take automatic protection measure in the event of lost communication between the aircraft and remote controller, or low battery situation. ([33] 33)</td>
</tr>
<tr>
<td>Starpoint™ Positioning System</td>
<td>Enables the aircraft to hover precisely in areas where GPS signal is not available. ([34] 34)</td>
</tr>
</tbody>
</table>

### NOTE
A home point is usually memorized by the system each time as the point where the aircraft takes off. The home point can be repositioned via the app. ([40] 40) The altitude of the original home point remains unchanged.

### Supported Flight Modes

<table>
<thead>
<tr>
<th>Flight Modes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPS Mode</td>
<td>Stabilizes and holds the aircraft in position and altitude on stick release (requires at least 6 GNSS satellite signals), providing stable and smooth flight maneuvers, as well as safety features including Go Home, IOC and Failsafe.</td>
</tr>
<tr>
<td>ATTI Mode</td>
<td>Stabilizes and holds the aircraft in altitude on stick release. The ATTI mode provides more agility in flight control by commanding the attitude (roll and pitch angles) of the aircraft directly.</td>
</tr>
</tbody>
</table>

### Flight LED Indicator

The LED indicators on the aircraft can be found on both the front and rear arms. The front indicators help you identify the position of the aircraft’s nose, and the rear indicators show the current flight status of the aircraft.

The LED indicators will light up when you turn on the aircraft. The table below describes the meanings of the LED indicator’s statuses.

- ● Indicates solid light
- ○ Indicates slow flashing light
- ◎ Indicates quick flashing light
- R Indicates red colored light
- G Indicates green colored light
- Y Indicates yellow colored light

Example: “R-●” stands for RED SOLID light.

<table>
<thead>
<tr>
<th>Definitions of Flight LED Indicator Light Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>R-● (Front LEDs)</td>
</tr>
<tr>
<td>R&amp;G-○◎ (Rear LEDs)</td>
</tr>
<tr>
<td>R&amp;Y-○◎ (Rear LEDs)</td>
</tr>
<tr>
<td>G-◎ (Rear LEDs)</td>
</tr>
<tr>
<td>Y-◎ (Rear LEDs)</td>
</tr>
<tr>
<td>Y-○◎ (Rear LEDs)</td>
</tr>
<tr>
<td>Y-● (Rear LEDs)</td>
</tr>
</tbody>
</table>

NOTE
It is highly recommended to operate outdoor flights in GPS mode for maximum safety. ATTI mode is disabled by default, and GPS mode is always enabled when good GPS reception is available. ATTI mode can be enabled through the mobile app: Settings ( ) > Flight Control Settings ( ) > Advanced Settings > Enable ATTI Mode.
### Airplane Battery

The airplane battery is a rechargeable Li-Po battery with a capacity of 4900mAh specifically designed for the X-Star/X-Star Premium aircraft. It can only be charged with the charger supplied in the X-Star/X-Star Premium package, and can provide up to 25 minutes of continuous flight if fully charged.

#### Smart Features

The airplane battery features several smart functionalities for charge-discharge management that preserves battery life.

<table>
<thead>
<tr>
<th>Aircraft Battery Features</th>
</tr>
</thead>
<tbody>
<tr>
<td>Balancing</td>
</tr>
<tr>
<td>Communication</td>
</tr>
<tr>
<td>Charging Temperature Detection</td>
</tr>
<tr>
<td>LED Capacity Indicator</td>
</tr>
</tbody>
</table>
| Overcharging & Over-discharging Protection | • Stops charging when battery voltage reaches 17V.  
• Stops discharging when battery voltage reaches 10.8V. |

#### Aircraft Battery

- **Capacity Level Indicator Lights**
- **Power Button** – allows you to check the battery level and turn on/off the battery.

#### To turn on/off the battery

Press and hold the button for 3 seconds.

#### To check the battery level when the battery is powered off

Press the button.

The table below describes the corresponding battery levels indicated by the capacity indicator lights once you press the button.

<table>
<thead>
<tr>
<th>Battery Level Indicator Status While Discharging</th>
</tr>
</thead>
<tbody>
<tr>
<td>91%–100%</td>
</tr>
<tr>
<td>●●●●●</td>
</tr>
<tr>
<td>26%–40%</td>
</tr>
</tbody>
</table>

- ● - Indicates solid green light; ○ - Indicates flashing green light; □ - Indicates no light

---

**NOTE**

The rear LEDs will flash green light twice when a new parameter or waypoint setting has been acknowledged.
XI-5S Gimbal

The XI-5S camera gimbal is a quick-mount stabilized gimbal with three axes. It is specially designed to minimize camera vibration and deliver smooth aerial photographing.

It is powered through the aircraft battery, and therefore turned on at the same time with the aircraft. A self-test is performed each time when the gimbal starts up.

To install the gimbal

1. Match the Quick-mount Module attached to the gimbal and the Quick-mount Base at the bottom of the aircraft.
2. Slide the Quick-mount Module onto the Quick-mount Base towards the Lock direction ( ) indicated beside the Unlock button.

You will hear a clicking sound when the gimbal is properly installed.

To remove the gimbal

1. Hold the aircraft with one hand.
2. Hold the Quick-mount Module and press the Unlock button ( ) at the side of this module with another hand.
3. Slide the Quick-mount Module out towards the Unlock direction ( ) indicated beside the Unlock button.

The XI-5S camera gimbal for X-Star/X-Star Premium supports 2 working modes:

Stabilized Mode – enables stabilized camera tilting control for creative aerial photography by synchronizing the gimbal yaw movement with the aircraft.

FPV Mode – synchronizes the gimbal roll and yaw movements with the aircraft to provide a real-time video piloting experience from a first person view.
Camera

The **X-Star** and **X-Star Premium** are both equipped with a 4k UHD camera. The camera supports various shooting modes including single shot, burst shooting, AEB and time lapse. Videos can be recorded in MOV or MP4 formats, and photos can be saved in JPG or DNG formats. An HD live view from the camera can be displayed on your mobile device through the mobile app **Starlink™**.

Remote Controller

The remote controller enables wireless communication with the aircraft through a 5.8GHz radio frequency band. The maximum working range of the remote controller in an open area is about 500m when set as CE standard, or about 1000m (**X-Star**) / 2000m (**X-Star Premium**) when set as FCC standard.

The built-in 2.4GHz WiFi module of the **X-Star** remote controller and 900MHz HD video streaming module of the **X-Star Premium** remote controller allow video downlink from the aircraft for real-time flight and video data displayed on the app, enabling convenient control of aerial photography and remote piloting.

**IMPORTANT**

The X-Star network is only established when the aircraft, the remote controller and the mobile device are properly connected through the WiFi network (**X-Star**) or HD video streaming (**X-Star Premium**).

Functionality Description

1. **Antennas**
   - The left antenna transmits 5.8GHz RF signal to the aircraft for sending commands and receiving flight information.
   - Both antennas receive 2.4GHz WiFi signal (**X-Star**) or 900MHz HD video signals (**X-Star Premium**) from the aircraft and transfer the flight data and camera data to the connected mobile app.

2. **Mobile Device Holder**
   - Holds the mobile device with a 180° adjustable viewing angle for optimum visibility.

3. **Flight Information Panel**
   - Displays the flight status, warning messages and real-time instructions. (13)

4. **Left Command Stick**
   - Set by default: Upward / Downward and Turn Left / Turn Right

5. **Right Command Stick**
   - Set by default: Forward / Backward and Move Left / Move Right

6. **Strap Hole**
   - Attached to a neck strap for easy portability.

7. **Motor Starter**
   - Starts the motors.

8. **Take-off/Landing Button**
   - Commands the aircraft to take off or land.

9. **Power Button**
   - Press and hold for 2 seconds to turn on/off the remote controller. You will hear a buzz sound. The power button shows a solid green light when you turn on the remote controller.

10. **Go Home Button**
    - Commands the aircraft to return to the home point.

11. **Pause Button**
    - Commands the aircraft to stop moving temporarily and hover in position when necessary.

12. **Power Port**
    - Connected to the **X-Star/X-Star Premium** charger to charge the built-in battery of the remote controller.
Flight Information Panel

The LCD Flight Information Panel found on the X-Star/X-Star Premium remote controller is designed to provide you with intuitive information during the flight, including the flight status, warning messages, real-time instructions, etc. This section introduces the function of this panel.

Remote Controller Calibration

Every time you see Calibrate RC on the Flight Information Panel, please calibrate the two command sticks and the Gimbal Pitch Dial. You can calibrate your remote controller according to the following steps, or using the mobile app instead (p. 52).

To calibrate the remote controller

1. Turn off the remote controller, and then press and hold the ( ) and ( ) buttons simultaneously until the RC calibration screen appears as shown on the right. The two crossed bars represent the left and right command sticks, and the horizontal bar at the bottom stands for the Gimbal Pitch Dial.

2. Release both command sticks and the Gimbal Pitch Dial naturally to the central position. The three central rounds on the RC calibration screen will be highlighted successively.

3. Push both command sticks to the ends of their 4 directions, and turn the Gimbal Pitch Dial clockwise and counterclockwise to its 2 ends, holding respectively until you hear a beep. All the bars on the screen will be fully highlighted when your calibration is completed.

Binding

The remote controller and the aircraft are bound by default when both devices are powered up. However, when you change an aircraft or remote controller, or activate the RC Binding Button on the aircraft, you need to rebind your aircraft and remote controller.

<table>
<thead>
<tr>
<th>✅ Gimbal Pitch Dial</th>
<th>Turn the dial to control the tilt angle of the gimbal.</th>
</tr>
</thead>
<tbody>
<tr>
<td>✅ Flight Mode Switch</td>
<td>Switch between IOC, GPS and ATTI modes.</td>
</tr>
<tr>
<td>✅ Camera Settings Dial</td>
<td>Turn the dial to adjust the Advanced Camera Settings. (p. 41)</td>
</tr>
<tr>
<td>✅ Playback Button</td>
<td>Playback the captured images or videos. (Only functions when the remote controller is connected to the mobile app.)</td>
</tr>
</tbody>
</table>

| ✅ Support Stand | Holds up the remote controller at a 40 degree angle. |
| ✅ Shutter Button | Takes a photo. If burst mode is selected, the set number of photos will be taken with one press. |
| ✅ Record Button | Record a video. Press again to stop recording. |
| ✅ CAN-bus Port | Connects two remote controllers with one operator as the instructor and the other as the learner. (p. 54) |
| ✅ Micro-USB Port | Reserved port. |
| ✅ USB Port | Connects to a mobile device through a USB cable. |
To bind the aircraft and remote controller

1. Turn off the remote controller.
2. Turn on the aircraft.
3. Press and hold the **RC Binding Button** on the aircraft for about 3 seconds, and the binding indicator beside the **RC Binding Button** will flash slowly in green light indicating the aircraft is ready to rebind.
4. Press and hold the ( ) and ( ) buttons on the remote controller, and the binding indicator will turn to solid green light once your binding is successful.

**NOTE**
You may also use the app to bind the aircraft and remote controller via **Settings ( ) > RC Settings ( ) > RC Binding. ( 53)**

---

**Main Interface**

When the video link has been connected properly, the main interface will appear as follows:

<table>
<thead>
<tr>
<th>Indicator Lights</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>① GPS Signal</strong></td>
<td>Indicates the signal strength of GNSS satellites.</td>
</tr>
<tr>
<td><strong>② Video Link Signal</strong></td>
<td>Indicates the WiFi video signal (X-Star) or HD video signal (X-Star Premium) strength.</td>
</tr>
<tr>
<td><strong>③ Flight Orientation</strong></td>
<td>Indicates the tilt angle of the aircraft.</td>
</tr>
<tr>
<td><strong>④ Remote Controller Signal</strong></td>
<td>Indicates the control signal strength of the remote controller.</td>
</tr>
<tr>
<td><strong>⑤ Remote Controller Battery</strong></td>
<td>Indicates the battery level of the remote controller.</td>
</tr>
<tr>
<td><strong>⑥ Aircraft Battery</strong></td>
<td>Indicates the battery level of the aircraft.</td>
</tr>
<tr>
<td><strong>⑦ Flight Speed</strong></td>
<td>Indicates the flight speed of the aircraft.</td>
</tr>
<tr>
<td><strong>⑧ Pitch Angle</strong></td>
<td>Indicates the tilt angle of the camera.</td>
</tr>
<tr>
<td><strong>⑨ Flight Distance</strong></td>
<td>Indicates the horizontal distance between the aircraft and the home point.</td>
</tr>
<tr>
<td><strong>⑩ Flight Altitude</strong></td>
<td>Indicates the altitude of the aircraft relative to the home point.</td>
</tr>
<tr>
<td><strong>⑪ Flight Status Bar</strong></td>
<td>Displays the real-time flight status, the function of the button you have activated, and warning messages.</td>
</tr>
</tbody>
</table>

---

**Indicator Lights**

On the remote controller, there are 5 indicator lights in total. They are found on the Motor Starter ( ), the Take-off/Landing Button ( ), the Power Button ( ), the Go Home Button ( ), and the Pause Button ( ). Each of them shows a different status in a different situation.
The following table describes the definitions of the indicator light status.

- ● Indicates solid light
- R Indicates red colored light
- ○ Indicates flashing light
- G Indicates green colored light
- ◎ Indicates no light
- Y Indicates yellow colored light

Example: “R-●” stands for SOLID RED light.

- **G-●:** A. Sufficient battery when RC is in use  
  B. Fully charged in charging state with power on
- **G-◎:** In charging state with power on
- **Y-●:** Low battery warning
- **R-●:** In charging state with power off
- **R-◎:** In process of RC firmware upgrade
- **○:** A. Fully charged in charging state with power off  
  B. Power off while not in charging state

**Remote Controller Buzzer Alerts**

The built-in buzzer of the remote controller makes different alert sounds according to various status alarms, such as low battery warning, video link error or lost aircraft communication. The different alerts are described below.

<table>
<thead>
<tr>
<th>Remote Controller Buzzer Alerts</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Aircraft Low Battery Warning</td>
<td>1 quick beep every second (lasts for 5s), with 2 RC vibrations</td>
</tr>
<tr>
<td>(about 25%)</td>
<td></td>
</tr>
<tr>
<td>Aircraft Critical Low Battery Warning</td>
<td>5 quick beeps every second (last for 5s), with 5 RC vibrations</td>
</tr>
<tr>
<td>(about 15%)</td>
<td></td>
</tr>
<tr>
<td>RC Low Battery Warning (10%)</td>
<td>1 quick beep every second (lasts for 5s)</td>
</tr>
<tr>
<td>RC Critical Low Battery Warning (5%)</td>
<td>5 quick beeps every second (last for 3s), with 2 RC vibrations</td>
</tr>
<tr>
<td>Aircraft &amp; RC Communication Lost</td>
<td>2 quick beeps every second (last for 5s), with 1 RC vibration</td>
</tr>
<tr>
<td>Video Link Disconnected</td>
<td>3 quick beeps in 1 second</td>
</tr>
<tr>
<td>Compass Interference</td>
<td>3 beeps with 3 RC vibrations</td>
</tr>
<tr>
<td>Standby Notification Tone</td>
<td>3 beeps every 15 minutes of inactivity</td>
</tr>
</tbody>
</table>

**G-●:** Simply press the button shortly to activate the Pause function

**○:** 1s after you release each button

**Remote Controller Buzzer Alerts**

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<tr>
<td>Standby Notification Tone</td>
<td>3 beeps every 15 minutes of inactivity</td>
</tr>
</tbody>
</table>

**G-●:** Activate each button by holding for 2s until you hear a beep sound

**○:** 1s after you release each button

**G-◎:** The aircraft is performing the Go Home procedure

(Go Home Button)
Preparing the Flight

The X-Star/X-Star Premium features a user-friendly design that requires very simple assembly to get the aircraft ready to fly. However, it is essential to read and follow all the instructions and warnings in this manual prior to assembly, setup or use, in order to operate safely.

**WARNING**
Do not use incompatible components or alter this product in any way inconsistent with this manual. Failure to operate this product in a safe and responsible manner could result in injury or damage.

Preparing the Battery

Installing and Removing the Aircraft Battery

➢ To install the battery

1. Make sure the battery is powered off before installation.

2. Insert the battery into the aircraft battery compartment as shown on the right. The battery will firmly click in when it is properly installed.

➢ To remove the battery

1. Make sure the battery is powered off before removal.

2. Press and hold the top and bottom tabs on the battery, and pull it out slowly.

Charging

The aircraft battery and the remote controller can be charged simultaneously with the charger supplied in the X-Star/X-Star Premium package.

➢ To charge the aircraft and remote controller

1. Remove the battery from the aircraft and connect it to the charger.

**IMPORTANT**

- The aircraft battery should be fully charged before use for the first time.
- If the current battery level is ≥80%, turn on the battery before charging.

2. Connect the charging cable to the Power Port on your remote controller.
3. Connect the charger to a power outlet.
   • The battery level indicator lights on the aircraft battery will illuminate and indicate the current battery level during charging, and will turn off when the battery is fully charged.

<table>
<thead>
<tr>
<th>Battery Level Indicator Status While Charging</th>
</tr>
</thead>
<tbody>
<tr>
<td>&gt;95%</td>
</tr>
<tr>
<td><img src="image" alt="Solid Green" /></td>
</tr>
<tr>
<td>○</td>
</tr>
<tr>
<td><img src="image" alt="Flash Green" /></td>
</tr>
<tr>
<td>○</td>
</tr>
</tbody>
</table>

• The button on the remote controller will illuminate solid green light (when RC power on) or solid red light (when RC power off) during charging. When charging is completed, it is prompted on the Flight Information Panel, and you will hear two beep sounds.

4. When charging is completed, disconnect the charger and the aircraft battery/remote controller.

**NOTE**
For a full charge, the aircraft battery requires 1 hour and the remote controller requires 4.5 hours approximately.

---

### Preparing the Aircraft

Follow the instructions in this section to prepare the aircraft for a safe flight.

#### Removing Gimbal Holder

Remove the gimbal holder before powering up the aircraft to avoid damage. Pull out the attached gimbal holder carefully as illustrated below.

Reinstall the gimbal holder after using the aircraft to protect the gimbal from unwanted movements when not in use.

## Installing Propellers

### WARNING
Do not power up the aircraft while installing or removing the propellers.

### IMPORTANT
It is recommended to wear protective gloves when assembling or removing the propellers to protect you from the sharp edges. Use tools (e.g., wrench, plier, etc.) when necessary.

On each of the propellers there is one **Lock** icon and one **Unlock** icon indicating the rotate direction to fasten or unfasten the propellers.

- **Fasten the propeller by rotating the propeller in the indicated direction.**
- **Unfasten the propeller by rotating the propeller in the indicated direction.**

### To install the propellers

1. Remove the warning cards from motors after reading. Do not power up the aircraft.

2. Match two of the propellers with red nuts to the corresponding motors with red paint, and the other two with silver/black nuts to the unpainted motors.

3. Fasten the propeller by rotating in the direction indicated by the icon printed on the propeller.

### To remove the propellers

1. Power off the aircraft.

2. Unfasten the propeller by rotating in the direction indicated by the icon printed on the propeller.
**Preparing the Mobile Device**

By connecting your mobile device to the aircraft, the X-Star mobile app **Starlink™** configures your mobile device to perform as a First Person View (FPV) monitor and a ground station for remote piloting, flight configuration and waypoint navigation.

The **Starlink™** app works on both iOS and Android smart phones and tablets. You can download it from our official website, Google Play or App Store.

**Supported systems:**
- iOS 8.0 or later (only compatible with iPhone 5 or later iPhone models)
- Android 4.0 or later

**Installing the Mobile App – Starlink™**

Download and install the **X-Star/X-Star Premium** mobile app **Starlink™** according to the following procedures.

➢ **To install Starlink™:**

   A. Search in App Store/Google Play by entering the keyword **Starlink** (case insensitive) to download and install the app on your mobile device.

   ![App Store Icon](AppStoreIcon.png) ![Google Play Icon](GooglePlayIcon.png)

   **NOTE**

   The remote controller makes an alert sound after 15 minutes of inactivity, and turns off automatically after 30 minutes of inactivity.

   B. Download **Starlink™** from the official website:

      2. Download from **Support > Downloads > Software & App**
      3. Install the mobile app on your mobile device

   **NOTE**

   **Starlink™** will be updated regularly. Please check occasionally for latest updates.
Connecting the Mobile Device

The X-Star/X-Star Premium network is established when the aircraft, the remote controller and the mobile device are properly connected. This enables the mobile device to receive real-time flight data and video footage during flight so you can monitor flight maneuvers through the mobile app.

To connect the mobile device to the aircraft
1. Power up the remote controller and the aircraft successively.
2. Connect your mobile device.
   - X-Star:
     Turn on the WiFi connection on your mobile device, select X-Star_×××××× from the WiFi list, and enter the default password 99999999.
   - X-Star Premium:
     Use a USB cable to connect your mobile device to the USB Port on the back of the remote controller.
3. Launch the mobile app ( ) on your mobile device. When the connection is successful, the Home Page of the app displays Connected in the upper left corner, and the Flight Information Panel on the remote controller displays App Connected in the Flight Status Bar.

Calibrating the Compass

Make sure to calibrate the compass every time when flying in a new location. The rear 2 LEDs on the aircraft will show solid yellow light when the flight system detects compass deviation, indicating that you should change a place and calibrate the compass. If a drift occurs when the aircraft is hovering, the compass calibration is also necessary.

WARNING
The compass is very sensitive to electromagnetic interference that may cause compass error and poor flight. If you find the compass abnormal after calibration, move the aircraft to another location and try again.

Remember to meet the following requirements when carrying out compass calibration:
- Operate calibration outdoors (ideally on an open space such as a lawn).
- Be free from all magnetic interferences, such as magnetite or steel reinforcement found in concrete.
- Stay away from both underground and overhead power lines.
- Do not carry ferromagnetic materials (e.g., keys) with you.

To calibrate the compass:
1. Begin calibration with your app: Settings ( ) > Flight Control Settings ( ) > Compass Calibration, and follow the on-screen instructions that help you monitor the calibration status. When the calibration process has been initiated, the 4 LEDs on the aircraft will flash yellow light.
2. Hold the aircraft horizontally and rotate it until the 4 LEDs on the aircraft change into flashing green light, indicating that this step is completed successfully.
3. Hold the aircraft vertically and rotate it again with its nose facing downwards. When calibration succeeds, the 4 LEDs on the aircraft will illuminate solid green light for 5s.
After all pre-flight preparations have been done properly, take a few minutes to familiarize yourself with the controls of your X-Star/X-Star Premium by following the operation instructions described in this section before flying.

### IMPORTANT
Before flying the X-Star/X-Star Premium aircraft, make sure those who operate or come into contact with this product have read and understood all safety instructions presented throughout this manual.

### Preflight Checklist

Follow the steps below to carry out a full preflight check-up to maximize safety.

- The aircraft battery, the remote controller and the mobile device are fully charged.
- The gimbal holder is removed.
- The propellers are properly installed and are in good condition.
- The antennas of the remote controller are unfolded and well adapted for a good position to obtain the best transmission quality (28).
- The aircraft and the remote controller are bound.
- The mobile app is properly installed and your mobile device is connected to the aircraft.
- The camera view on the X-Star mobile app is synchronized with the mounted camera.
- The firmware has been updated to the latest version.
- Familiarize yourself with the flight controls.
- Your flight area is an open, unobstructed and uncrowded area.

### WARNING
- If the calibration is unsuccessful, the 4 LEDs on the aircraft will illuminate solid yellow light. In this case, repeat the above steps to try again.
- If severe drifting occurs during flight or the aircraft seems unstable for any reason, please land immediately.

### NOTE
- When the mobile app displays instructions or alerts, please perform the required task in time to ensure your operation can be carried out successfully.
- You can also start the calibration process with the remote controller by pressing ( ) and ( ) simultaneously for 2 seconds. Then continue to perform Steps 2 and 3 to complete the procedure.

### Flight Operations
Remote Controller and Flight Operations

The remote controller has 2 command sticks designed for convenient remote flight controls for aerial maneuvers, including aircraft ascent/descent, left/right rotation, forward/backward and left/right sideway movements.

⚠️ WARNING
When the GPS signal is not strong enough, the aircraft will not take off in GPS mode.

For the aircraft to receive maximum signal strength from the controller, position the two antennas so that they are parallel to each other and that their pointing direction is perpendicular to the direction of the aircraft's position, as shown in the images below.

Motor Start-up and Take-off

Start the motors before commanding the aircraft to take off.

✅ NOTE
The aircraft will not take off if the battery level is 15% or lower.

- When the motors are turned on, use one of the following methods to take off the aircraft:
  - Takeoff/Landing Button: Hold for 2s
  - Ascent Stick: push gently
  - If you command the aircraft to take off using , the aircraft will ascend automatically to a height of 4 meters.

NOTE
only be activated after 3 seconds upon motor start-up, and does not work in ATTI Mode.

⚠️ WARNING
Do not block any of the air vents located beside the motors. Make sure the motors have cooled down completely before you touch it.

Command Stick Control

The aircraft reacts to the control of the command sticks through the RF transmission. The flight speed depends on the magnitude of the stick commands.

🔥 TIPS
For beginners, it is recommended to move the command sticks lightly and slowly to keep the aircraft flying in a controllable speed.

- Left Command Stick
  - Ascent/Descent – commands the aircraft to ascend by pushing the stick upward, and descend by pushing it downward.
Smart Flight Features

- Intelligent Orientation Control (IOC)

To activate the IOC function during flight, slide the Flight Mode Switch at the side of the remote controller to the left.

IOC mode is also known as Carefree Mode. It is used to keep the aircraft’s direction controls locked regardless of its nose direction. It is most useful when you are unable to observe the nose direction of the aircraft. IOC works only in GPS mode, and has 2 control modes: Home Lock and Course Lock.

Home Lock

The Forward/Backward and Move Left/Right command stick controls are always in the radial or tangential directions of the aircraft position relative to the home point regardless of the aircraft nose direction.

Course Lock

The Forward/Backward and Move Left/Right command stick controls are set in the parallel and perpendicular directions, respectively, to the reference line between the home point and the point where the IOC is activated regardless of the aircraft nose direction.

NOTE

- The flight direction is relative to the home point instead of the location of the pilot.
- IOC mode can only be activated when the aircraft is at least 10 meters away from you.

NOTE

The controls illustrated above are set as the default command stick mode (Mode 2). The left command stick controls aircraft ascent/descent and left/right rotation; The right command stick controls aircraft forward/backward and left/right sideway movements. You can change the control settings via the app: Settings (Settings) > RC Settings > Command Stick Mode.
- **Go Home**

  The **Go Home** function only works in **GPS** mode. To manually activate the **Go Home** function, you can press the **Go Home** button ( ) on the remote controller.

  When the **Go Home** command has been successfully received, the aircraft automatically maneuvers itself to return directly and land at the preset home point. Make sure there are no buildings or other obstacles in the flight path.

  When **Go Home** is activated, the remote controller’s functionality will be disabled temporarily while the aircraft returns to the home point. The remote controller’s functionality can be regained during this period, allowing you to stop the aircraft Going Home when you consider it is safe.

  **IMPORTANT**

  - When the **Go Home** function is activated, for safety reasons, if the aircraft is hovering at the altitude lower than 30 meters, it will ascend to an altitude of 30 meters above the home point before starting to return. You can adjust the Go Home altitude in the app: **Settings** ( ) > **Flight Control Settings** ( ) > **Go Home Altitude** ( )

  - If the **Go Home** function is activated within 10 meters radius from the home point, the aircraft will land automatically onsite.

  ➢ **To manually regain control of the aircraft during Go Home procedure:**

    Push the **Ascent** stick to the position of 90% in range and hold for 2 seconds (illustration below as mode 2). The aircraft will stop flying towards the home point and may fly upward slightly when the remote controller control is recovered.

    ![](image)

    Alternatively, you can simply press the **Pause Button** ( ) to regain control of your aircraft.

- **Failsafe**

  The **Failsafe** function is designed to help your X-Star/X-Star Premium automatically return home or land onsite when necessary.

  - **Communication Lost**

    **Failsafe** will be triggered 5s after the communication between your aircraft and remote controller gets lost.

    If GPS is available when **Failsafe** is activated, the aircraft will start the **Go Home** procedure automatically.

    If GPS is unavailable (i.e. less than 6 satellites are found) when **Failsafe** is activated, the aircraft will hover for 10s. If 6 or more satellites are found during this period, the aircraft will start the **Go Home** procedure; otherwise, the aircraft will land onsite.

  - **Low Aircraft Battery**

    **Failsafe** will also be activated if one of the following low battery conditions are met.

    A. Your aircraft’s battery constantly calculates the required battery level for the aircraft to return to the home point from its current location. When the battery level reaches the minimum level required for the aircraft to return to the home point, **Failsafe** will be activated and your aircraft will automatically **Go Home**. You can regain control of the aircraft during the **Go Home** process ( ).

    B. Anytime your aircraft’s remaining battery level reaches 25% (**Low Battery Warning**), **Failsafe** will be activated and your aircraft will automatically **Go Home**. If you choose to regain control during this process, the aircraft will automatically land onsite when the remaining battery level reaches 15% (**Critical Low Battery Warning**). In this case, you may push the **Ascent** stick to stop the aircraft landing and command it to fly away from the current location for a safe landing in case of an emergency.

  **NOTE**

  - If the aircraft is only within 50m away from the home point when your aircraft’s battery level reaches 25% (**Low Battery Warning**), the aircraft will not perform the **Go Home** procedure.

  - If GPS is unavailable when **Failsafe** is activated at **Low Battery Warning**, Go Home procedure will not be executed. In this case, the aircraft will land automatically when the remaining battery level reaches 15% (**Critical Low Battery Warning**).
**Starpoint™ Positioning System**

The Starpoint™ Positioning System installed on the X-Star/X-Star Premium functions through a monocular camera ① and two ultrasonic sensors ② on the bottom of the aircraft. The sensors help to identify the current height of the aircraft through ultrasound, and the camera obtains location information through image analysis. With the help of the Starpoint™ Positioning System, the aircraft can hover in place more precisely when flying indoors or in other environments where the GPS signal is unavailable.

**TIPS**

- Always keep the monocular camera lens clean for a clear view.
- Do not use other 40KHz ultrasonic devices nearby when the Starpoint™ Positioning System is activated.

**Landing and Motor Shut-down**

The aircraft can be landed manually, automatically, or passively.

**IMPORTANT**

The aircraft must be landed gently on a flat surface to avoid damage.

**Manual Landing**

You can manually land the aircraft whenever and wherever you want by maneuvering the command sticks on the remote controller.

- **To land the aircraft manually**
  1. Maneuver the aircraft to the desired position for landing.
  2. Release the command sticks when the aircraft reaches the target position to let it hover.
  3. Push the **Descent** stick steadily and gently to land the aircraft.

- **To shut down the motors**

When the aircraft has properly landed, use one of the methods below to shut down the motors:

- **Descent Stick:** Push to the end and hold for 2s
- **Both Command Sticks:** Hold toe-in or toe-out for 2s

**WARNING**

The toe-in action will always shut down the motors even if the aircraft is in midair. Please be extra cautious and use this feature only in an emergency, e.g., when the aircraft gets out of control.

**NOTE**

- The Starpoint™ Positioning System is activated by default when the aircraft is turned on.
- The Starpoint™ Positioning System works both in GPS and ATTI modes and is only valid when the aircraft is between 30cm and 300cm above the surface.

**IMPORTANT**

The performance of the Starpoint™ Positioning System is affected by the brightness and texture of the surface over which the aircraft is flying. The ultrasonic sensors may not function accurately above sound-absorbing materials. Please try to avoid the following situations:

- Flying over a monochrome surface (e.g. pure black, white, or red) or a highly reflective surface (e.g. water, transparent surfaces).
- Flying over extremely dark or bright surfaces, or in an area where the lighting changes frequently.
- Flying over surfaces with unclear patterns or texture, or highly repeating patterns or texture (e.g. tiles with the same design).
- Flying over surfaces (e.g. thick carpet) that can absorb or deflect sound waves.
- Flying at a high speed: over 8m/s at a 2-meter height, or over 4m/s at a 1-meter height.
- Flying over moving surfaces or objects.
**Automatic Landing**

You can use the ( ) button on the remote controller to land the aircraft automatically from its current hover position with one single click.

- **To land the aircraft automatically with the ( ) button:**
  1. Maneuver the aircraft to the desired position for landing.
  2. Release the command sticks when the aircraft reaches the target position to let it hover.
  3. Press and hold the ( ) button for 2 seconds until you hear a beep sound.
  4. The aircraft will descend to land and shut off its motors automatically. During descent, you will also have control of the pitch, roll and yaw adjustments.

**TIPS**

- During the automatic descent process, you can regain control by pushing the Ascent stick to at least 90% level and maintaining for 2 seconds. (32)

**NOTE**

- Automatic landing is also available in ATTI mode but you should control the attitude of the aircraft manually.
- It is recommended that you land the aircraft immediately when Low Battery Warning (25% or lower) is shown, i.e., the rear LEDs on the aircraft illuminate flashing red light, and the ( ) button on the remote controller lights up in solid yellow light.

**Passive landing**

When Failsafe is triggered by any of the following conditions, the aircraft will be forced to land onsite automatically.

- **Low Battery Warning** is activated in non-GPS environment.
- **Critical Low Battery Warning** is activated.

**Using the Starlink™ App**

The X-Star/X-Star Premium application, Starlink™, is a full-featured program allowing aircraft control, flight data review, remote camera shooting, preset-waypoint navigation, general settings and so on. Your mobile device will perform as the central monitor for remote piloting control, aerial photographing and filming, and flight parameter tuning to achieve optimal flight performance.

**Home Page**

**FLIGHT RECORD**

View detailed record of all your flights such as time, distance and actions taken.

**ACADEMY**

View documents and videos, such as Packing List, Quick Guide, User Manual and Guided Tour.

**LEARN MORE**

Slide the center of the screen to find the aircraft you wish to learn more about and tap on it to get more information.

**MEDIA**

View and edit the photos and videos that you have downloaded.

**STORE**

Enter Autel Robotics’ online store where you can purchase the products and accessories.

**ME**

Register or log into your Autel Robotics account.
How to Connect
Slide the center of the screen to choose your aircraft and tap this button to follow the pop-up instructions to connect your mobile device. When your connection is successful, this button turns to green and displays Connected.

NOTE
When your aircraft is used for the first time, you will be guided to the registration page after the connection is completed. Please follow the on-screen instructions to activate your X-Star/X-Star Premium:

1. Create an account and set a password for your account.
2. Name your X-Star/X-Star Premium.
3. Select a Command Stick Mode, Parameter Unit and System.
4. Confirm that the Beginner Mode is enabled. This mode is enabled by default when you use the product for the first time, and you may disable Beginner Mode through the app: Settings > Flight Control Settings > Beginner Mode (51).

START
Enter the camera screen for a First Person View.
When your mobile device has been connected to the aircraft, the system will run a self-check to ensure it is safe to fly. You can check the overall status in a prompted window and eliminate the abnormal conditions before your flight.

First Person View (FPV)
This interface synchronizes your screen display with the on-board camera for a real-time first person view, allowing you to perform various camera operations and configurations for aerial photography.

Flight Control Panel
- AUTOPilot
  Command the aircraft to fly automatically according to the intelligent flight mode you have selected, including Orbit, Follow and Waypoint modes. (44)
- TAKE-OFF / LAND
  Command the aircraft to take off or land.
- GO HOME
  Command the aircraft to return to the specified home point.
- HOME POINT
  Choose a new location as your home point. Options include the location where you are standing and the real-time location of the aircraft when you tap this icon. The rear LEDs of the aircraft will flash green light quickly for 3 seconds, indicating that the home point reset is successful.

Aircraft Status Bar
- DISTANCE
  The horizontal distance between the aircraft and the home point.
- ALTITUDE
  The altitude of the aircraft relative to the home point level.
- FLIGHT SPEED
  The current flying speed of the aircraft.
- REMAINING TIME
  The remaining time for the aircraft to fly.
- BATTERY LEVEL
  The current battery level of the aircraft.
**STARPOINT™ POSITIONING SYSTEM**
The distance between the surface and the Starpoint™ Positioning System's sensors. This icon is highlighted only when the Starpoint™ Positioning System is in working state.

**FLIGHT STATUS**
- The arrow indicates the yaw angle of the aircraft's nose.
- The colored ring indicates the current battery level of the aircraft. The green bar is present when there is abundant battery. The yellow bar indicates Low Battery and you should let your aircraft Go Home. The red bar means Critical Low Battery and the aircraft will land onsite.

**Camera Operation Panel**

**PITCH CONTROL BUTTON**
Tap this button to open the Pitch Scroll Bar which you can scroll up and down to control the camera pitch movement. A camera pitch angle indicator will show up accordingly on the upper right corner of this button.

**PLAY BUTTON**
This icon displays the most recent photo/video taken. You may tap it to view and download/delete your photos and videos one by one or in groups.

**RECORD BUTTON**
Tap this button to record a video. Tap it again to stop recording. Video Settings are available in ( ).

**SHUTTER BUTTON**
Tap this button to take a photo. Photo Settings are available in ( ). Before taking a photo, select a shooting mode (Single Shot, Burst Shooting, AEB, Time Lapse) from Photo Settings. This icon may appear differently depending on different shooting modes you have chosen.

**ADVANCED CAMERA SETTINGS**
Automatic Settings ( ) allows you to adjust EV; Manual Settings ( ) allows you to adjust ISO and Shutter Speed.

**CAMERA SETTINGS**
Perform Photo Settings ( ), Video Settings ( ) and Camera Settings ( ).

<table>
<thead>
<tr>
<th>(* default value)</th>
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</thead>
<tbody>
<tr>
<td>Mode</td>
</tr>
<tr>
<td>Size</td>
</tr>
<tr>
<td>Format</td>
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<tr>
<td>Style</td>
</tr>
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<td>WB</td>
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<td>Color</td>
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<th>(* default value)</th>
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<tbody>
<tr>
<td>Standard</td>
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<tr>
<td>Histogram</td>
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<td>Over Exposure Warning</td>
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<td>Subtitle, SRT Files</td>
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<tr>
<td>Anti-Flicker</td>
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<tr>
<td>Grid</td>
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<tr>
<td>File Index Mode</td>
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<tr>
<td>Reset Settings</td>
</tr>
<tr>
<td>Format SD Card</td>
</tr>
<tr>
<td>Version</td>
</tr>
</tbody>
</table>

**NOTE**
Please format the SD card only via the Starlink™ app. The camera may not be able to recognize the SD card if you format it using other devices.
The three function icons on the right provide different options for you to view the map:

<table>
<thead>
<tr>
<th>Icon</th>
<th>Name</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>⬤</td>
<td>Location</td>
<td>Choose the area around the home point.</td>
</tr>
<tr>
<td>🩹</td>
<td>Choose the area around the aircraft’s location.</td>
<td></td>
</tr>
<tr>
<td>🌌</td>
<td>Compass</td>
<td>Lock/unlock the compass of the map.</td>
</tr>
<tr>
<td>⬤</td>
<td>Map View</td>
<td>Choose a map view from Normal, Hybrid and Satellite view.</td>
</tr>
</tbody>
</table>

**Autopilot**

The Autopilot function includes a series of smart flight modes that command your aircraft to fly in a specific pattern automatically, providing a carefree piloting experience for you. Tapping (      ) leads you to the Autopilot options below. The (   ) button on the upper right corner grants access to the instructions for each mode:

1. **Orbit Mode**

When Orbit mode is activated, the aircraft flies in a circle with the camera fixed on a point of interest (POI). Please follow the app to perform Orbit:

1. Choose a POI you prefer from below:

---

**IMPORTANT**

During Autopilot Mode, please always keep a clear path for the aircraft as it cannot avoid obstacles that come into the flight path autonomously.

---

**General Information Bar**

**SETTINGS**

Tap this icon to open the Settings page where you can manage Flight Control, Remote Controller, Video Link, Aircraft Battery, Gimbal and General Settings. (50)

**SYSTEM STATUS**

Displays the real-time status of your aircraft.

**FLIGHT MODE**

The information displayed on this icon varies depending on the current flight mode of the aircraft, including GPS, ATTI, IOC, Follow, Orbit, Failsafe, etc..

**GPS SIGNAL**

Displays the current GPS signal strength.

**Map Split Screen**

In the FPV interference, you will see a smaller split screen at the bottom left displaying the map of the surrounding area of your aircraft. Tap on this screen to switch to the map view as shown below.

To view different areas, you can zoom in, zoom out or move the map.
3. A Go Home Altitude setting will pop up for you to set a safe altitude for the aircraft to perform Go Home at low battery level. Once you click OK, your aircraft will initiate Autopilot.

4. Use the left and right command sticks to adjust the position of the aircraft as illustrated on the right side of the screen. You can change the orbit direction (CW/CCW) or turn the aircraft’s nose towards the POI (Face POI).

5. Tap Pause to let the aircraft hover, or tap Exit to exit Orbit mode.

**NOTE**

The orbit radius can only be set between 10m and 100m. When flying within 10m or beyond 100m radius centering the POI, the aircraft will adjust its orbit radius to 10m and 100m respectively.

- **Follow Mode**

In Follow mode, the aircraft tracks you as you move with its nose pointing at you. The speed will depend on your moving speed but cannot exceed the flight speed you set in the app: Settings ( ) > Flight Control Settings ( ) > Flight Speed.

The table below illustrates how to control the relative position of the aircraft:

<table>
<thead>
<tr>
<th>POI</th>
<th>Orbit Radius</th>
</tr>
</thead>
<tbody>
<tr>
<td>Aircraft</td>
<td>Distance between O and R.</td>
</tr>
<tr>
<td>Me</td>
<td>Distance between you and R.</td>
</tr>
<tr>
<td>New</td>
<td>Distance between R and the point you choose on the map.</td>
</tr>
</tbody>
</table>

**A.** Move your aircraft from the current location O to your desired location R to set the orbit radius.

**B.** Tap on the top box in the right panel on the screen to input a number to manually adjust the orbit radius between the aircraft and the POI. Then decide the laps, the orbit direction (CW/CCW), and whether the aircraft is to Hover or Go Home when Orbit is finished. The aircraft will automatically face the POI when you initiate Orbit mode. You can still control the camera any time you wish. Click Start when ready.

- **Aircraft:** The current location of the aircraft
- **Me:** Your current location
- **New:** Pin a new point within a safe round zone displayed on the map

2. Follow one of the methods below to set the orbit radius before starting the program.

- Move your aircraft from the current location O to your desired location R to set the orbit radius.
using the remote controller during Follow mode.

<table>
<thead>
<tr>
<th>![Image]</th>
<th>![Image]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Adjust the altitude of the aircraft.</td>
<td>Change the direction of the aircraft’s nose.</td>
</tr>
<tr>
<td>![Image]</td>
<td>![Image]</td>
</tr>
<tr>
<td>Adjust the distance between you and the aircraft.</td>
<td>Command the aircraft to follow you in a circular course leftward or rightward.</td>
</tr>
</tbody>
</table>

## NOTE
- **Follow** mode is valid within 100 meters radius centering the mobile device. However, the aircraft will not turn its nose towards the mobile device when the horizontal distance between them is less than 3 meters.
- You can choose a location (your current position or the initial home point) for your aircraft to return to when **Failsafe** is activated in **Follow** mode.

### IMPORTANT
- **Orbit** and **Follow** modes cannot be activated when the aircraft is less than 10 meters high above the home point. Once you have activated **Follow** or **Orbit** mode, the altitude limit will be cancelled.
- In **Follow** or **Orbit** mode, if the GPS signal of your mobile device is too weak, the aircraft will switch to hover mode until the GPS signal quality becomes acceptable again. Follow/Orbit mode will be cancelled automatically after 15 seconds of poor GPS reception of the mobile device.

#### Waypoint Mode
This mode allows the aircraft to fly in a preset route according to the waypoints you have set. You can command the aircraft to fly along the route you have saved in **Favorites**, or create a new route.

### IMPORTANT
For **X-Star Premium**, you can use this function directly and the map will be downloaded automatically. For **X-Star**, if you use the app on an Android mobile device, you need to download the map before using this function for the first time; this is not necessary if you use an iOS device, as the iOS system allows simultaneous connection with the aircraft self-generated WiFi network and the 3G/4G network.

- **To download the map on X-Star**
  1. Disconnect your mobile device from the X-Star WiFi network.
  2. Connect your mobile device to the Internet and enter the map from Map Split Screen to download the map.
  3. Reconnect your mobile device to the X-Star WiFi network and come back to this function.

- **To perform Waypoint mode**
  1. Choose one of the following 3 ways to set up your waypoints.
    - **Aircraft** - Select **Aircraft** from the drop-down box of **Waypoint Location**. Move your aircraft to a target position and tap **Mark Waypoint** to set it as one of your waypoints. The rest of your waypoints can be done in the same manner. The **Delete Waypoint** button is used to remove the last waypoint you set. When you have confirmed all the waypoints, tap **Finish**.
    - **Draw on Map** - Select **Draw on Map** from the drop-down box of **Waypoint Location** and your screen will be switched to the map. Move your finger to draw a route on the map, and the waypoints will be identified automatically according to your route. The **Clear Waypoints** button is used to delete the entire route. When you have confirmed your route, tap **Finish**.
3. Set a safe altitude for the aircraft to perform Go Home at low battery level.

4. When the aircraft is performing a Waypoint mission, you may adjust the aircraft’s speed with the right command stick and command its nose to face next waypoint with the Face Next Waypoint button. The Exit button is used to exit this mode. Tapping (☆) on the upper right corner will save the current route into Favourites.

**TIPS**

To terminate the Waypoint mission at any point, perform one of the following actions:

- Regain control of the aircraft by sliding the Flight Mode Switch on the remote controller to ATTI position. (Only available when ATTI is enabled on the app) The aircraft will terminate the mission and respond to the remote controller.

- Press (.leave) on the remote controller and hold for 2 seconds. The aircraft will terminate the mission and land at the home point.

- Push the Ascend stick to the position of 90% in range and hold for 2 seconds. This is the same with the method to regain control of the aircraft during Go Home. (32)
6. Go Home Altitude

Set a safe altitude for your aircraft to Go Home automatically in case of an emergency. If you set the Go Home Altitude to a certain value, the aircraft will adjust its altitude to this value before returning to the home point. The default Go Home Altitude is 30m.

7. Advanced Settings

- Enable ATTI Mode
  
  Switch this button on so you can activate ATTI mode on the remote controller directly, as this mode is disabled by default to prevent accidental disabling of GPS mode.

- IOC Mode
  
  You can choose from Home Lock and Course Lock as you need. (31)

- Front LED Indicator Lights
  
  Slide this button to turn on or turn off the two red front LED indicator lights. These LEDs help you to identify the aircraft’s nose direction during flight.

- Read Flight Data
  
  Connect your aircraft to a computer with a USB cable to read the flight data. Then you need to reboot the aircraft before use.

Remote Controller Settings

The Remote Controller Settings function grants access to Gimbal Pitch Dial Speed, RC Binding, RC Calibration, Command Stick Mode and RC Language Settings and Teaching Mode.

1. Gimbal Pitch Dial Speed

  Slide the scroll bar left or right to adjust the speed of the Gimbal Pitch Dial on the remote controller.

2. RC Calibration

  This function includes the calibration of the Left Command Stick, Right Command Stick and Gimbal Pitch Dial. You will only need to calibrate your remote controller when using it for the first time or after your remote controller has been replaced.

  The horizontal bar on the upper part of the screen represents the Pitch Control Dial, and the two crossed bars on the sides represent the left and right command sticks.

  ➤ To calibrate the remote controller
I. Release the two command sticks and the Gimbal Pitch Dial to their central position and tap **Start**.

II. Push both command sticks and turn the Gimbal Pitch Dial to their complete range of motion. The progress bars will be in response to your calibration. Below is an example for illustration.

III. After each bar has been highlighted 100%, tap **Finish** and your remote controller calibration is completed.

3. **RC Binding**
   
   Press the **Bind** button and then hold the **RC Binding Button** on the aircraft for 3s as instructed on the app to bind your aircraft and remote controller. You will be prompted when this is done successfully.

4. **Command Stick Mode**
   
   Choose a command stick mode to control your aircraft. There are 3 modes available: Mode 1, Mode 2 and Mode 3, controlling the aircraft in different manners. Below are the illustrations of these 3 modes.

5. **RC Language**
   
   Set the language displayed on the LCD **Flight Information Panel**.

6. **Teaching Mode**
   
   This mode creates a simultaneous connection between an aircraft and two remote controllers for teaching purposes. One of the remote controllers (which is bound with the aircraft) is set as **Learner**, and the other is set as **Instructor**. When **Instructor** is operating, **Learner**'s functions will be disabled automatically (excluding the **Gimbal Pitch Dial**). This helps **Instructor** to demonstrate the operation methods and gain control of the aircraft from **Learner** in an emergency.

   To activate **Teaching Mode**, connect two remote controllers with a CAN cable, and designate them on the app respectively. To designate the remote controller as **Learner**, connect your mobile device to the remote controller bound with the aircraft and tap the **Learner** button on the app (**Settings** > **Remote Controller Settings** > **Teaching Mode**). To designate the other remote controller as **Instructor**, disconnect your mobile device from **Learner** and connect it to the other remote controller, or use another mobile device to connect it, then tap the **Instructor** button on the app. **Instructor** and **Learner** can be set in a random order.

   **NOTE**
   
   To connect your mobile device and the remote controller, you need to use WiFi for **X-Star** and a USB cable for **X-Star Premium**.  
   
   **Video Link Settings**
   
   For the **X-Star**, you can rename the WiFi SSID and reset the password in this
NOTE
To reset the WiFi video link, toggle the Flight Mode Switch back and forth quickly for at least 4 times. The remote controller will make a beep sound when the WiFi SSID and password have been reset to the default values.

For the X-Star Premium, you can check the noise condition of each channel and choose the one with minimum noise.

Gimbal Settings
This section allows you to adjust gimbal settings.

1. Gimbal Mode
   Choose a working mode for your gimbal from Stabilized mode and PFV mode. (8)

2. Adjust Gimbal Roll
   You can adjust the roll axis of your gimbal slightly while watching the camera view to find the best angle for your photography.

Aircraft Battery Settings
You can also enter this section by tapping ( ) on the Aircraft Status Bar. This function allows you to view the current status and general information of the aircraft battery. Low Battery Warning and Critical Low Battery Warning settings are also available in this section.

NOTE
For your own safety, the Low Battery Warning cannot be set below 25%, i.e., the minimum battery level for Go Home; and the Critical Low Battery Warning cannot be set below 15%, i.e., the minimum battery level for landing.

- General Settings
  1. Parameter Unit
     Choose your preferred unit system: Imperial or Metric.
  2. Tutorial
     Slide this button to display or hide the tips for your operation.
  3. Map
     • Show Flight Route
       Slide this button to display or hide your flight route on the map.
     • Calibrate Coordinates (For Mainland China)
       Slide this button to enable or disable the map calibration.
5

Maintenance and Service

Firmware Upgrade

To optimize the performance of your X-Star/X-Star Premium, firmware updates will be provided on a regular basis. You can download the latest firmware (Flight Control, Gimbal, Camera, Remote Controller, etc.) in one package from our official website. When a firmware update is available, you will be prompted by the app once it is connected to the aircraft.

IMPORTANT
Before updating, please make sure:
• The four motors have stopped completely.
• The battery level of both your aircraft and remote controller is not less than 25%.
• There is enough space available in your camera’s SD card to store the firmware upgrade data.

➢ To download and upgrade the firmware
2. Insert the SD card into your computer and extract the downloaded file (into a .bin file extension) into your SD card. Then remove your SD card from the computer.
3. Turn on the remote controller and aircraft.
4. Insert the SD card into the aircraft to start the upgrade process automatically. You can check the real-time upgrade status displayed on the Flight Information Panel.
5. Reboot the remote controller and aircraft before use.
If the camera is powered off during video recording
• Keep the Micro-SD card inside the camera. Restart the camera and wait until the video files are recovered (partial data may be lost)

If acquisition of the WiFi SSID fails
• Check if both the aircraft and the remote controller are powered on
• Make sure WiFi is enabled on the mobile device

If the aircraft is out of sight and the video link is lost
• Activate Go Home procedure to have the aircraft automatically return or activate IOC procedure (Home Lock) to manually navigate it to return

If the mobile app is accidentally closed when the aircraft is executing a Waypoint mission
• If the app is closed when the flight mission is under execution, the aircraft will continue to execute the given command
• You can regain control of the aircraft with the remote controller manually at any time

Storage and Maintenance Instructions

To ensure optimum performance of the product, we advise you read and follow the maintenance instructions in this section carefully.

• Keep the devices in a clean, dry and ventilated environment within normal operating temperatures.
• Keep the devices out of sunlight when not in use
• Dry your hands before using the devices.
• Use a soft cloth with alcohol or a mild window cleaner to clean the lens of the camera, instead of any abrasive cleansers, detergent or chemicals.
• Ensure that the battery charger does not come in contact with conductive material.
• Avoid dropping your devices, especially on a hard surface. Check it in detail after any crash or impact, and contact a local Autel Robotics agent in time if you have any problem.
• Only use the battery chargers or other accessories authorized by Autel Robotics. Failure to do so may void the warranty.

Customer Service

This section contains information regarding technical support, repair service, and
Warranty

Autel Robotics (the Company) warrants to the original retail purchaser of this product, that should this product or any part thereof during normal consumer usage and conditions, be proven defective in material or workmanship that results in product failure within the valid warrant period from the date of purchase, such defect(s) will be repaired, or replaced (with new or refurbished parts or products) at the Company’s option, with Proof of Purchase, without charge for parts or labor directly related to the defect(s). Some states do not allow limitation on how long an implied warranty lasts, so the above limitations may not apply to you.

The Company shall not be liable for any incidental or consequential damages arising from the use, misuse, or mounting of the device. The extent of Autel Robotics’ liability under this warranty is limited to the repair and replacement provided above and, in no event, shall its liability exceed the purchase price paid by purchaser for the product.

Please visit www.autelrobotics.com for details of the limited periods warranted for the different parts of this product.

This warranty does not apply to:

- Batteries that cycle-charged for more than 200 times;
- Products subjected to abnormal use or environmental conditions, accident, mishandling, neglect, unauthorized alteration, misuse, improper installation or repair, or improper storage;
- Products with signs of tempering or altering of the serial number label, waterproof mark, etc.;
- Damage resulting from connection to, or use of any accessory or other product not approved or authorized by the Company;
- Defects in appearance, cosmetic, decorative or structural items such as framing and non-operative parts.
- Products damaged from external causes including but not limited to fire, water, dirt, sand, battery leakage, blown fuse, theft or improper usage of any electrical source.

Technical Support

If you have any questions or concerns regarding our products, please contact us by:

- Telephone: (844)-898-0290 (U.S.A.)
- Email: support@autelrobotics.com
- In person: local distributors or agents

Repair Service

If it is necessary to return your device for repair, please fill in and submit the repair service form on http://www.autelrobotics.com. The following information is required:

- Contact name
- Email address
- Mailing address
- Telephone number
- Product name
- Complete description of the problem with photo attachments
- Proof-of-purchase for warranty repairs
- Preferred method of payment for non-warranty repairs

Autel Robotics’ support team will review your application within 72 hours after receiving your application. After a preliminary evaluation of the problem, our customer support will contact you for further updates or follow-ups.
pilots’ safe and legal operations of the product. The flight restricted areas are divided into 2 protection categories.

**Category I:** Major airports and flight areas where manned aircrafts operate at low altitudes

- **Take-off Restricted Zones (No-Fly Zones)**
  These areas are set within 2.4km around the central point of specified airports.

- **Altitude Restricted Zones**
  In these areas, the aircraft is only allowed to fly within limited altitudes. From 8km to 2.4km around the airport’s central point, the flight altitude decreases progressively from 120m to 10.5m.

- **Warning Zones**
  Once the aircraft enters a region within 8.1 km from the central point of the airport, the app will prompt a warning message.

**NOTE**
If the aircraft enters any Altitude Restricted Zones, its maximum allowable altitude will be reduced accordingly. If the aircraft enters any Take-off Restricted Zones, it will land automatically. You should pay special attention to the warning messages displayed on your app.

**Category II:** Sensitive areas and institutes such as military sites and border lines between countries

- **Take-off Restricted Zones (No-Fly Zones)**
  These areas are set within 1km around the center of the specified sites where take-off and flight are prohibited.

- **Warning Zone**
  Once the aircraft enters the region within 2km from the center of the site, the
### Technical Specifications

#### Aircraft Specifications

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hover Precision</td>
<td>Horizontal: ±2.5m; Vertical: ±1m;</td>
</tr>
<tr>
<td>Max Yaw Rate</td>
<td>150°/s</td>
</tr>
<tr>
<td>Max Inclination Angle</td>
<td>GPS Mode: 20°; ATTI Mode: 25°</td>
</tr>
<tr>
<td>Max Ascent/Descent Speed</td>
<td>Ascent: 6m/s; Descent: 3m/s</td>
</tr>
<tr>
<td>Max Horizontal Speed</td>
<td>15m/s</td>
</tr>
<tr>
<td>Diagonal Wheelbase</td>
<td>352mm</td>
</tr>
<tr>
<td>Propeller Size</td>
<td>9.4”x5.5”</td>
</tr>
<tr>
<td>Video Link Frequency</td>
<td>X-Star: 2.412GHz–2.462GHz</td>
</tr>
<tr>
<td></td>
<td>X-Star Premium: 902MHz–928MHz</td>
</tr>
<tr>
<td>Receiver Frequency</td>
<td>5.727GHz–5.799GHz</td>
</tr>
<tr>
<td>Flight Modes</td>
<td>GPS, ATTI, IOC</td>
</tr>
<tr>
<td>Operating Environment Temperature</td>
<td>-10°C–45°C (14°F–113°F)</td>
</tr>
<tr>
<td>Storage Temperature</td>
<td>-20°C–80°C (-4°F–176°F)</td>
</tr>
<tr>
<td>Weight (Battery &amp; Propellers included)</td>
<td>1.42kg</td>
</tr>
</tbody>
</table>

#### Aircraft Battery Specifications

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Battery Type</td>
<td>Rechargeable Li-Po battery</td>
</tr>
<tr>
<td>Capacity</td>
<td>4900mAh</td>
</tr>
<tr>
<td>Battery Voltage</td>
<td>14.8V</td>
</tr>
</tbody>
</table>

#### Camera Gimbal Specifications

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Current</td>
<td>650mA@12V (Non-video Mode)</td>
</tr>
<tr>
<td></td>
<td>760mA@12V (Video Mode)</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>12V</td>
</tr>
<tr>
<td>Operating Temperature</td>
<td>-10°C–50°C</td>
</tr>
<tr>
<td>Weight</td>
<td>175g (Camera incl.)</td>
</tr>
<tr>
<td>Dimensions (Damping Device excl.)</td>
<td>88mm X 76.5mm X 80mm</td>
</tr>
<tr>
<td>Control Accuracy</td>
<td>Pitch: ±0.015°; Roll: ±0.015°; Yaw: ±0.015°</td>
</tr>
<tr>
<td>Max. Angular Velocity</td>
<td>Pitch: ±300°/S; Yaw: ±360°/S</td>
</tr>
<tr>
<td>Controllable Range</td>
<td>Pitch: 0°–90°; Yaw: ±50°</td>
</tr>
</tbody>
</table>

#### Camera Specifications

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Environment Temperature</td>
<td>0°C–40°C (32°F–104°F)</td>
</tr>
<tr>
<td>Still Photography Modes</td>
<td>Single shot</td>
</tr>
<tr>
<td></td>
<td>Burst shooting: 3/5/7 frames</td>
</tr>
<tr>
<td></td>
<td>Auto Exposure Bracketing (AEB): 3/5</td>
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<tr>
<td></td>
<td>Bracketed frames at 0.7EV Bias</td>
</tr>
<tr>
<td></td>
<td>Time-lapse</td>
</tr>
<tr>
<td>Video Recording Modes</td>
<td>UHD: 4096x2160p 24/25, 3840x2160p 24/25/30</td>
</tr>
<tr>
<td></td>
<td>QHD: 2704x1520p 24/25/30/48/50/60</td>
</tr>
<tr>
<td></td>
<td>FHD: 1920x1080p 24/25/30/48/50/60/120</td>
</tr>
<tr>
<td></td>
<td>HD: 1280x720p 24/25/30/48/50/60/240</td>
</tr>
<tr>
<td></td>
<td>SUPERVIEW: 1920x1080p 24/25/30/48/50/60/120</td>
</tr>
<tr>
<td>Max. Field of View</td>
<td>108°</td>
</tr>
<tr>
<td>Supported SD Card Types</td>
<td>Micro-SD card</td>
</tr>
<tr>
<td></td>
<td>Storage capacity: 4GB - 64GB</td>
</tr>
<tr>
<td></td>
<td>Class level: Class 10 or UHS-1 rating required</td>
</tr>
<tr>
<td>File Formats</td>
<td>FAT32/exFAT</td>
</tr>
<tr>
<td></td>
<td>Photo: JPG/DNG/JPG+DNG</td>
</tr>
<tr>
<td></td>
<td>Video: MOV/MP4</td>
</tr>
</tbody>
</table>

#### Charging Environment Temperature

<table>
<thead>
<tr>
<th>Temperature</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>10°C–45°C</td>
<td>(50°F–113°F)</td>
</tr>
</tbody>
</table>

#### Discharging Environment Temperature

<table>
<thead>
<tr>
<th>Temperature</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>5°C–45°C</td>
<td>(41°F–113°F)</td>
</tr>
</tbody>
</table>

#### Storage Temperature & Humidity

<table>
<thead>
<tr>
<th>Temperature</th>
<th>Humidity</th>
</tr>
</thead>
<tbody>
<tr>
<td>-10°C–45°C</td>
<td>45%–85%</td>
</tr>
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</table>

#### Camera Specifications

<table>
<thead>
<tr>
<th>Mode</th>
<th>Video Resolution</th>
</tr>
</thead>
<tbody>
<tr>
<td>UHD</td>
<td>4096x2160p 24/25, 3840x2160p 24/25/30</td>
</tr>
<tr>
<td>QHD</td>
<td>2704x1520p 24/25/30/48/50/60</td>
</tr>
<tr>
<td>FHD</td>
<td>1920x1080p 24/25/30/48/50/60/120</td>
</tr>
<tr>
<td>HD</td>
<td>1280x720p 24/25/30/48/50/60/240</td>
</tr>
<tr>
<td>SUPERVIEW</td>
<td>1920x1080p 24/25/30/48/50/60/120</td>
</tr>
</tbody>
</table>

#### File Formats

- FAT32/exFAT
- Photo: JPG/DNG/JPG+DNG
- Video: MOV/MP4
## Remote Controller Specifications

<table>
<thead>
<tr>
<th>Feature</th>
<th>X-Star</th>
<th>X-Star Premium</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>RF Receiver Operating Frequency</strong></td>
<td>5.727GHz~5.799GHz</td>
<td></td>
</tr>
<tr>
<td><strong>Video Link Frequency</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X-Star</td>
<td>2.412GHz~2.462GHz</td>
<td></td>
</tr>
<tr>
<td>X-Star Premium</td>
<td>902MHz~928MHz (America)</td>
<td>915MHz~928MHz (Australia)</td>
</tr>
<tr>
<td><strong>Operating Temperature</strong></td>
<td>-20°C<del>60°C (-4°F</del>140°F)</td>
<td></td>
</tr>
<tr>
<td><strong>Charging Temperature</strong></td>
<td>5°C<del>45°C (41°F</del>113°F)</td>
<td></td>
</tr>
<tr>
<td><strong>Storage Temperature</strong></td>
<td>Less than 1 month: -10°C<del>45°C (14°F</del>113°F) 1<del>6 months: -10°C</del>35°C (14°F~95°F)</td>
<td></td>
</tr>
<tr>
<td><strong>Communication Distance</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X-Star</td>
<td>CE: 500m; FCC: 1000m</td>
<td></td>
</tr>
<tr>
<td>X-Star Premium</td>
<td>FCC: 2000m</td>
<td></td>
</tr>
<tr>
<td><strong>Operating Current/Voltage</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X-Star</td>
<td>750mA/3.7V</td>
<td></td>
</tr>
<tr>
<td>X-Star Premium</td>
<td>350mA/3.7V (App disconnected)</td>
<td>1400mA/3.7V (App connected)</td>
</tr>
<tr>
<td><strong>Battery</strong></td>
<td>6000mAh rechargeable Li-Ion Battery</td>
<td></td>
</tr>
<tr>
<td><strong>Power Consumption</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X-Star</td>
<td>2.8W</td>
<td></td>
</tr>
<tr>
<td>X-Star Premium</td>
<td>5.2W</td>
<td></td>
</tr>
<tr>
<td><strong>Weight (battery included)</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X-Star</td>
<td>830g</td>
<td></td>
</tr>
<tr>
<td>X-Star Premium</td>
<td>840g</td>
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</table>